2019

MATHEMATICS

(Major)

Paper: 5.4

(Rigid Dynamics)

Full Marks: 60

Time: 3 hours

The figures in the margin indicate full marks for the questions

- **1.** Answer the following questions: $1 \times 7 = 7$
 - (a) Write down the moment of inertia of a solid sphere of radius a and mass M about a diameter.
 - (b) Define equimomental systems.
 - (c) State the theorem of parallel axes on moment of inertia.
 - (d) Define the centre of oscillation of a compound pendulum.
 - (e) What is the principle of conservation of energy?
 - (f) A particle moving freely in space requires three coordinates (x, y, z), to specify its position. What is the degree of freedom of the particle?
 - (g) What are generalized coordinates?

- 2. Answer the following questions:
- $2 \times 4 = 8$
- (a) A particle of mass 4 units is placed at the point (-1, -1, 1). What is the product of inertia of the particle about OX OY; and OY OZ?
- (b) A particle of mass 3 units is located at the point (2, 0, 0). The particle rotates about O with angular velocity $\vec{\omega} = \hat{k}$. Find the angular momentum of the particle about O.
- (c) A rigid body with one point fixed rotates with angular velocity w and has angular momentum Ω. Prove that the kinetic energy is given by

$$T = \frac{1}{2} (\vec{\omega} \cdot \vec{\Omega})$$

- (d) A particle of mass m moves in a conservative force field. Write the Lagrangian function.
- **3.** Answer the following questions: $5 \times 3 = 15$
 - (a) Show that the moment of inertia of a rectangular lamina of mass M and sides 2a, 2b about a diagonal is

$$\frac{2M}{3} \frac{a^2b^2}{a^2+b^2}$$
Or

Find the product of inertia of a semicircular wire about diameter and tangent at its extremity.

- (b) State and prove d'Alembert's principle.
- (c) Show that the momental ellipsoid at the centre of an elliptic plate is

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \left(\frac{1}{a^2} + \frac{1}{b^2}\right)z^2 = \text{constant}$$
Or

Show that a uniform rod of mass M is kinetically equivalent to three particles, rigidly connected and situated one at each end of the rod and its middle point, the masses of the particles being $\frac{1}{6}M$,

$$\frac{1}{6}M$$
 and $\frac{2}{3}M$.

4. A rod of length 2a, is suspended by a string of length l, attached to one end, if the string and rod revolve about the vertical with uniform angular velocity and their inclinations to the vertical be θ and ϕ respectively, show that

$$\frac{3P}{a} = \frac{(4\tan\theta - 3\tan\phi)\sin\phi}{(\tan\phi - \tan\theta)\sin\theta}$$

(a) A rough uniform board of mass m and length 2a, rests on a smooth horizontal plane and a man of mass M walks on it from one end to the other. Find the distance through which the board moves in this time.

(b) A circular board is placed on a smooth horizontal plane and a body runs round the edge of it at a uniform rate. What is the motion of the board?

5. (a) Prove that the time of complete oscillation of a compound pendulum is

$$2\pi \sqrt{\frac{k^2}{gh}}$$

where k is the radius of gyration of the body about a fixed axis and h is the distance of centre of inertia of the body from the fixed axis.

(b) Set up the Lagrangian for a simple pendulum and obtain an equation describing its motion.

6. A uniform sphere rolls down an inclined plane, rough enough to prevent any sliding.

Discuss the motion.

Or

Obtain the equation of motion of a rigid body under impulsive forces.

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(b) A circular board is placed on a smooth horizontal plane and a body runs round the edge of it at a uniform rate. What is the motion of the board?

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5. (a) Prove that the time of complete oscillation of a compound pendulum is

$$2\pi\sqrt{\frac{k^2}{gh}}$$

where k is the radius of gyration of the body about a fixed axis and h is the distance of centre of inertia of the body from the fixed axis.

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(b) Set up the Lagrangian for a simple pendulum and obtain an equation describing its motion.

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6. A uniform sphere rolls down an inclined plane, rough enough to prevent any sliding. Discuss the motion.

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Or

Obtain the equation of motion of a rigid body under impulsive forces.

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